

LA-2300 Series Linear Actuator

Table of Contents

General Information	2-3
Introduction	2
Receiving/Inspection	2
Storage	2
Equipment Return	2
Identification Label.....	3
Abbreviations Used in This Manual	3
General Actuator Description	3
Basic Models	3
Product Specifications	4
Installation	5
Typical Wiring Diagrams	6-7
Start-up/Calibration	8-9
Troubleshooting Guide	10-11
Component Location Drawing	12-13
Maintenance	14
Gear and Drive Nut Selection	15
Parts List and Recommended Spares	16-17
Major Dimensions	18-19

Due to wide variations in the terminal numbering of actuator products, actual wiring of this device should follow the print supplied with the unit.

GENERAL INFORMATION

INTRODUCTION

Jordan Controls, Inc., designs, manufactures, and tests its products to meet many national and international standards. For these products to operate within their normal specifications, they must be properly installed and maintained. The following instructions must be followed and integrated with your safety program when installing, using and maintaining Jordan Controls products:

- Read and save all instructions prior to installing, operating and servicing this product.
- If you do not understand any of the instructions, contact your Jordan Controls representative for clarification.
- Follow all warnings, cautions and instructions marked on, and supplied with, the product.
- Inform and educate personnel in the proper installation, operation and maintenance of the product.
- Install equipment as specified in Jordan Controls installation instructions and per applicable local and national codes. Connect all products to the proper electrical sources.
- To ensure proper performance, use qualified personnel to install, operate, update, tune and maintain the product.
- When replacement parts are required, ensure that the qualified service technician uses replacement parts specified by Jordan Controls. Substitutions may result in fire, electrical shock, other hazards, or improper equipment operation.
- Keep all product protective covers in place (except when installing, or when maintenance is being performed by qualified personnel), to prevent electrical shock, personal injury or damage to the actuator.

WARNING

Before installing the actuator, make sure that it is suitable for the intended application. If you are unsure of the suitability of this equipment for your installation, consult Jordan Controls prior to proceeding.

WARNING - SHOCK HAZARD

Installation and servicing must be performed only by qualified personnel.

WARNING - ELECTROSTATIC DISCHARGE

This electronic control is static-sensitive. To protect the internal components from damage, never touch the printed circuit cards without using electrostatic discharge (ESD) control procedures.

RECEIVING/INSPECTION

Carefully inspect for shipping damage. Damage to the shipping carton is usually a good indication that it has received rough handling. Report all damage immediately to the freight carrier and Jordan Controls, Inc.

Unpack the product and information packet—taking care to save the shipping carton and any packing material should return be necessary. Verify that the items on the packing list or bill of lading agree with your own.

STORAGE

If the product will not be installed immediately, it should be stored in a clean, dry area where the ambient temperature is not less than -20° F. The actuator should be stored in a non-corrosive environment. The actuator is not sealed to NEMA 4 until the conduit entries are properly connected.

EQUIPMENT RETURN

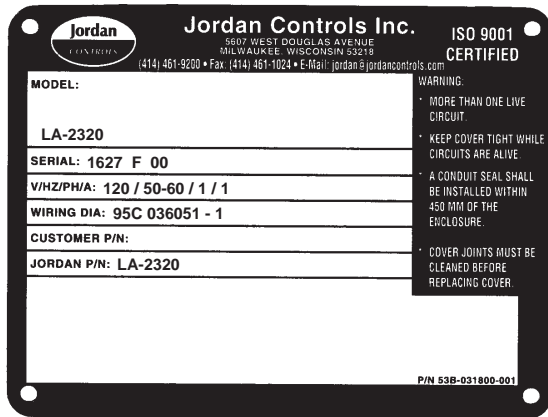
A Returned Goods authorization (RG) number is required to return any equipment for repair. This must be obtained from Jordan Controls. (Telephone: 414/461-9200) The equipment must be shipped, freight prepaid, to the following address after the RG number is issued:

Jordan Controls, Inc.
5607 West Douglas Avenue
Milwaukee, Wisconsin 53218
Attn: Service Department

To facilitate quick return and handling of your equipment, include:
RG Number on outside of box
Your Company Name, Contact Person, Phone/Fax No.
Address
Repair Purchase Order Number
Brief description of the problem

GENERAL INFORMATION

IDENTIFICATION LABEL



MODEL NUMBER: LA23 20 Series

SERIAL NUMBER: 1627 C 00
 Sequential Number ——— Year Built
 ——— Month Built

ABBREVIATIONS USED IN THIS MANUAL

A or Amps	Ampere
AC	Alternating Current
° C	Degrees Celsius
CW	Clockwise
CCW	Counterclockwise
DC	Direct Current
° F	Degrees Fahrenheit
G	Earth Ground
Hz	Hertz
kg	Kilogram
L	Line (power supply)
lbs.	Pounds
lbf.	Lbs. Force
LVDT	Linear Variable Differential Transformer
mA	Milliamp
mfd	Microfarad
mm	Millimeters
N	Newton (force)
NEMA	National Electrical Manufacturing Association
Nm	Newton Meter
NPT	National Pipe Thread
Ph	Phase
PL	Position Limit Switch
RPM	Revolutions per Minute
sec.	Second
TL	Thrust Limit Switch
Vac	Volts ac
Vdc	Volts dc
VR	Variable Resistance
W	Watt

GENERAL ACTUATOR DESCRIPTION

The LA-2300 series actuators are electrically operated, bi-directional linear devices. They are designed for strokes to 36 inches (914 mm) and thrusts to 750 lbf (3336 N). The drive motor may be single or three phase ac.

Options Include:

- Up to four independently adjustable limit switches
- Contactless feedback
- Potentiometer position feedback
- Thermostatically controlled anti-condensation heater
- Integral or remote servo-amplifiers
- Trunnion and flange mounting
- 4 to 20mA position feedback

The LA-2300 series include 120/240 Vac single phase models and 240/480 Vac three phase models. These actuators are controlled by “switched” power inputs or by a remotely installed servo-amplifier.

The LA-2300/AD-8130 series feature an integral servo-amplifier. They require 120 or 240 Vac (depending on model) unswitched, single phase line voltage input and a dc analog command signal for a complete, closed-loop positioning system in a compact enclosure.

BASIC MODELS

LA-2320, LA-2390 are single phase ac, three wire, plug reversible models. They are compatible with Jordan Controls remotely located AD-8000 Series servo amplifiers, MT-6220 manual remote control with position readout, or any bi-directional contact type control.

These actuators may also be equipped with an integral model AD-8130 servo amplifier that features loss of signal detection for current command signal inputs and can be calibrated to allow the actuator to lock-in-place or drive to a preset position should the command signal drop below 3.8mA. Also included is a dynamic brake circuit to increase positioning accuracy.

The LA-2315 is a three phase ac, plug reversible model compatible with Jordan Controls remotely located AD-8900 series servo amplifier or any bi-directional contact type control.

LA-2300 SERIES PRODUCT SPECIFICATIONS

GENERAL SPECIFICATIONS

Maximum Speed: 2.0 in./sec. (50.8 mm/sec.)

Maximum Thrust: 750 lbf. (3336 N)

Maximum Breakaway Thrust: 1500 lbf. (6672 N)

Speed/Thrust Chart:

Model	in. per sec. / lbf. (mm per sec. / N)			
LA-2315	0.2/750 (5.1/3336)	0.4/300 (5.1/1334)	0.8/190 (10.2/845)	2.0/75 (17.8/334)
LA-2320	0.2/500 (5.1/2224)	0.4/750 (5.1/3336)	0.8/340 (10.2/1512)	2.0/130 (17.8/578)

Breakaway thrust is twice the maximum thrust

Stroke: 6 to 36 in. (152 to 914 mm)

Lubrication & Type: Permanently lubricated, Amoco-Amolith Rykon All-Weather Premium Grease #2

Gearing: Hardened steel spur gear train, self-locking

Temperature: -40° F to 150° F (-40° C to 65° C)

Environment Rating: Dust ignition-proof for Class II, Division I, Groups E, F and G, and Type 4 (IP65) indoor and outdoor

Enclosure Material: Cast Aluminum Alloy

Approximate Weight: 40 lbs. (18kg)

Mounting: Clevis mount in any position.
Trunnion (not available with 6 in. stroke).
Flange (not available with 6 in. stroke).

Duty Cycle: 25%: LA-2315
20%: LA-2320, LA-2390

ELECTRICAL SPECIFICATIONS

Power Requirements:

Model	Input Power Volts/PH/Hz	Current (Amps)	
		Run	Stall
LA-2320	120/1/50-60	2.5	2.9
LA-2315	240/480/3/50-60	0.4/0.2	1.3/0.65
LA-2390	240/1/50-60	1.1	1.6

Input Voltage Tolerance: +/-10%

Conduit Entry: Two, 3/4 NPT.

Field Wiring: To barrier terminal blocks.

OPTIONS

Anti-condensation Heater: 120/240 Vac, 30W

Two auxiliary position limit switches: 10A,
120/240 Vac

Contactless Feedback: Hall Effect

Potentiometer Feedback, 1000 ohm: 2 Watt Max. dc

4-20mA Feedback Transmitter:

Isolated, loop-powered 12-36 Vdc at 25 mA.

Maximum Load (ohms) = $\frac{\text{Power Supply Voltage} - 8}{0.020A}$

Servo-Amplifier Model AD-8130: 120/240 Vac. (For more information see Jordan Controls IM-0607).

Accuracy: +/-1.0% of SPAN

Repeatability: 0.5% of SPAN

Hysteresis: 0.5% of SPAN

Linearity: +/-1.0% of SPAN

Input Deadband: Adjustable

Input Sensitivity: 0.25% of Deadband

Loss of Signal: Stays in place or runs to pre-set on current command signals dropping below 3.8 mA

Command Signal Inputs: Field selectable

4 to 20 mA (200 ohm impedance)

0 to 5 or 0 to 10 Vdc (100,000 ohm impedance)

High and Low Trim: Adjustable

MOUNTING

Refer to installation dimensions on the installation print sent with the actuator. The rear cover (opposite the ram) must have clearance so it can be removed for adjustments and interconnect wiring.

The actuator is mounted with pins through the rear and front clevises. The rear clevis is normally the stationary end. The device to be positioned must be such that it will allow retraction and extension. Side loading must be avoided. Side loading will lead to excessive operating thrust which will cause premature bearing failure. The device to be positioned must not require greater thrust than the rating of the actuator. Mount the rear clevis to the stationary actuator support device first, then move the traveling portion of the device to the front clevis and mount it.

As an option, trunnion or flange mounting is available on actuators with 12 inch (305 mm) or greater strokes. Dimensional details of this style of mounting are shown on page 18 of this manual.

INSTALLATION WIRING

The wiring diagrams on page 6 shows the fundamental connections for standard three-wire reversible single-phase AC motor and three phase AC models.

The wiring diagram on page 7 shows the fundamental connections for single phase AC actuators with an integral AD-8130 servo-amplifier.

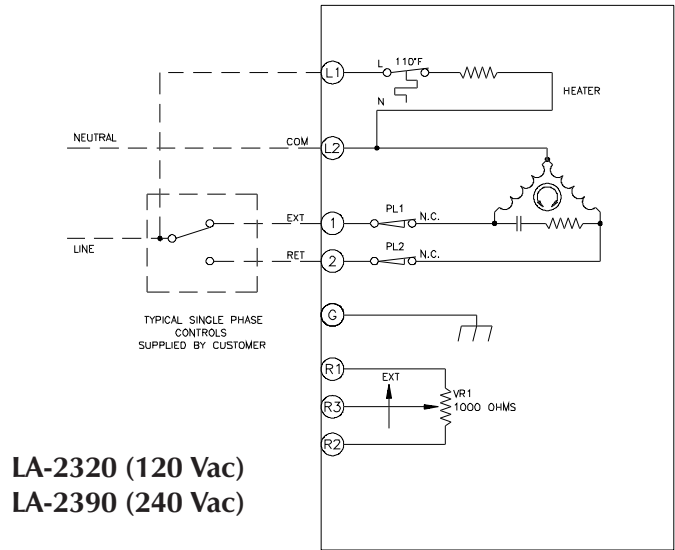
A terminal strip is located inside the rear enclosure cover at the rear clevis end of the actuator. Two 3/4 inch NPT conduit entries are available for field use. See the installation dimension drawing on the last page of this manual for their location.

CAUTION: On standard single-phase wiring, the position limit switches are wired directly in the motor circuit and protect it at the extremes of travel. Three phase AC units must have these limit switches wired into the controlling device to cause end of travel shutdown. Care must be taken in wiring these to the controlling device so that the appropriate direction of control is turned off when that direction's limit switch is actuated. If care is not taken in phasing the equipment, damage may occur to the actuator or driven load. Do not run the actuator into the mechanical limit of travel.

- All wiring should be done in accordance with prevailing codes by qualified personnel.
- Typical wiring diagrams are shown on pages 6-7. **Actual wiring should follow the wiring diagram supplied with the actuator.**
- Fusing must be installed in line power, and should be of the slow blow type.
- Wiring must be routed to the actuator through one of the two conduit openings. One conduit will contain input power and earth ground wires. The other conduit would then contain low level input and output signal wiring.
- It is required that all low level signal wiring be a shielded type with the shield grounded at source common.
- After installation, it is required that all conduits be sealed to prevent water damage and to maintain NEMA 4 enclosure rating.

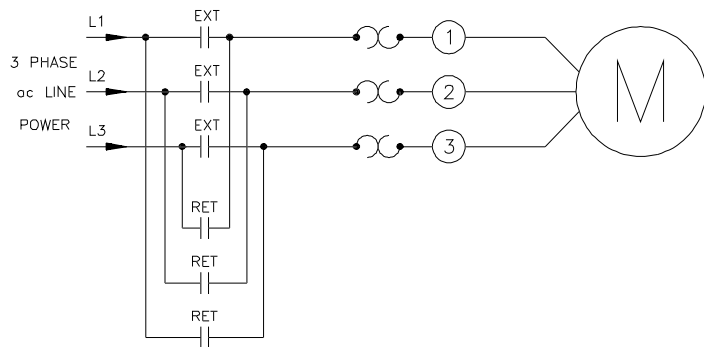
TYPICAL WIRING DIAGRAMS

ACTUATOR WITHOUT A BUILT-IN AMPLIFIER

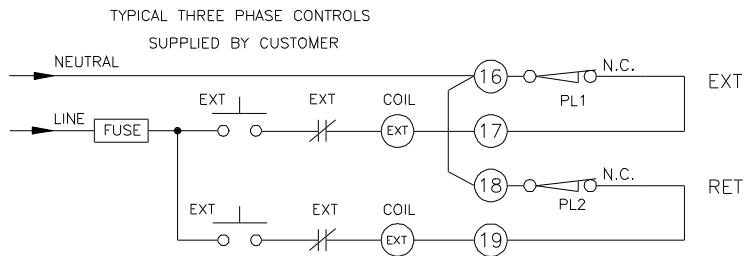


Actuator Action	AC Power Applied to Terminals	
	L2 + 1	L2 + 2
Viewing Actuator Ram	Extend	Retract

LA-2315 SERIES 3 PHASE AC ACTUATOR

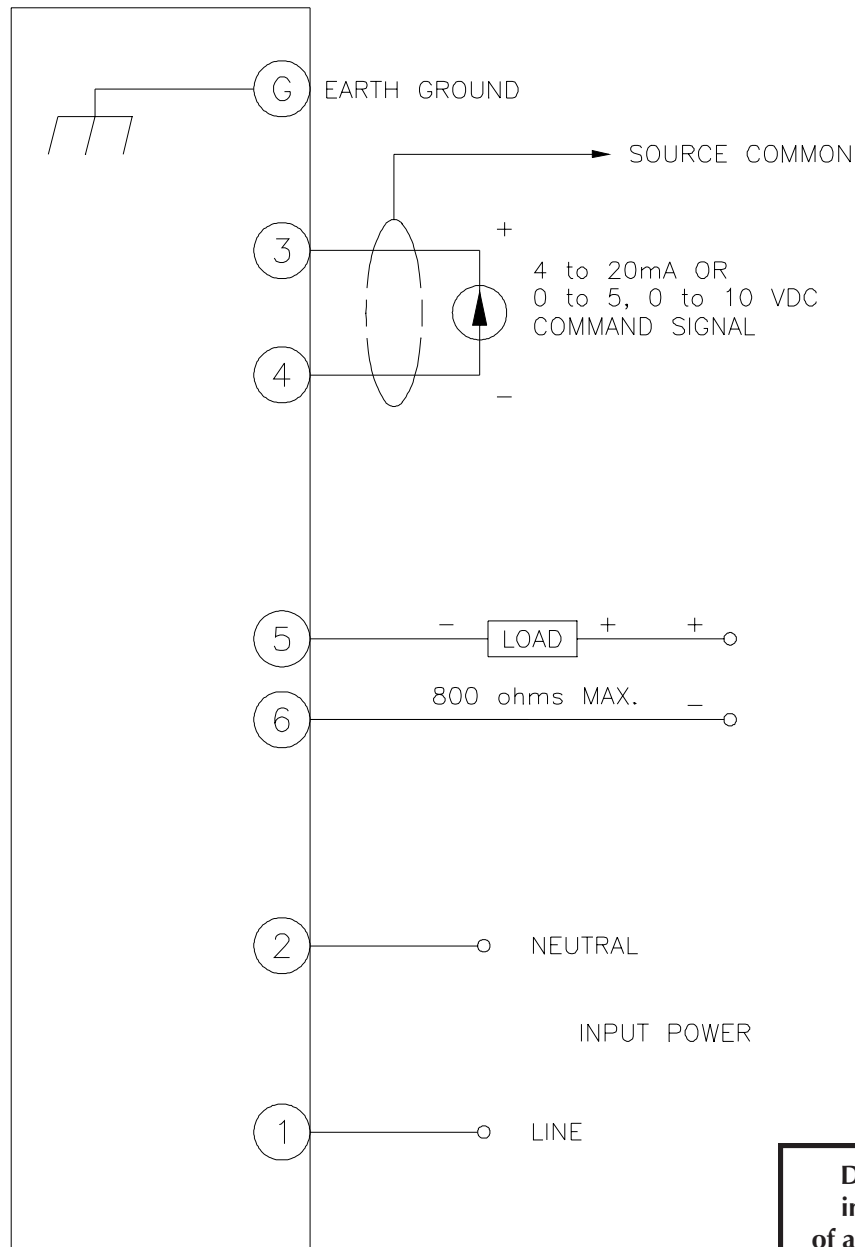


Due to wide variations in terminal numbering of actuator products, actual wiring should follow the print supplied with the actuator.



TYPICAL WIRING DIAGRAM

LA-2300 SERIES ACTUATORS WITH A BUILT-IN AD-8130 AMPLIFIER (120/240 Vac, Single Phase, 50-60 Hz)



**Due to wide variations
in terminal numbering
of actuator products, actual
wiring should follow the print
supplied with the actuator.**

Notes:

1. All references to actuator ram movement are as viewed facing the front clevis.
2. An increasing command signal will result in ram extension.
3. Command signal input:
 - 4 to 20 mA into a 200 ohm impedance
 - 0 to 5 or 0 to 10 Vdc into a 100,000 ohm impedance

START UP & CALIBRATION

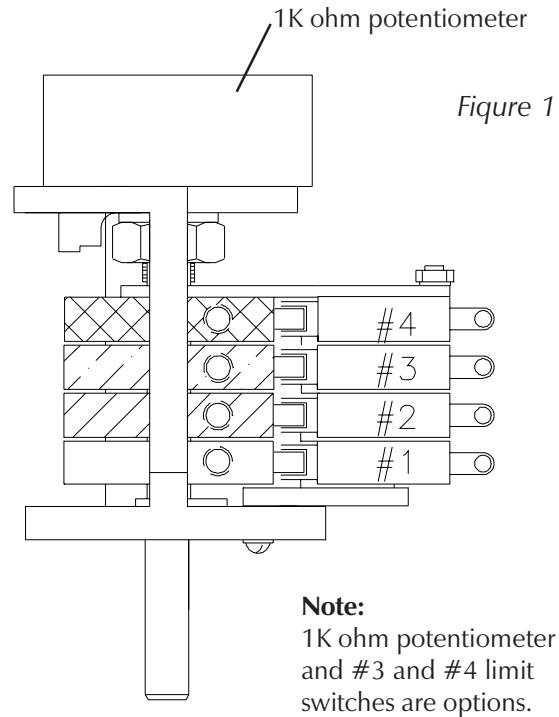
A. LIMIT SWITCH ADJUSTMENT PROCEDURE

(see Figure 1)

The limit switch assembly features two independently adjustable position limit switches. The setting of one switch does not affect the setting of the other. Limit switch #1 (PL1) is set to stop the actuator at the actuator fully extended position. Limit switch #2 (PL2) is always set to stop the actuator at the actuator fully retracted position. Each limit switch is activated by an aluminum cam with a detent. When the cam roller falls into this detent, the limit switch goes to its normal state. To readjust the limit switches for the required actuator stroke, the following methods are recommended:

FOR ACTUATOR WITHOUT A POTENTIOMETER

1. Loosen both set screws in PL2 cam (set screws are 120° apart). Rotate PL2 cam until the indent of the cam and the roller begin to mate and the limit switch activates (when you hear a “click”). Tighten the set screws.
2. Energize the motor and run front clevis to the fully extended position. Loosen both the set screws of PL1 cam and manually rotate the cam until the indent of the cam and the roller begin to mate and the limit switch activates (when you hear a “click”). Tighten the set screws.
3. The end of travel position limits PL1 and PL2 are now set for full stroke of the actuator.
4. Apply electrical power and run the actuator through its range to check for proper limit switch adjustment.



FOR ACTUATOR WITH A POTENTIOMETER

1. With no power applied to the circuits, connect an ohm meter across the potentiometer wiper arm and the “zero” (retract) end of the pot.
2. Follow steps 1 through 4 in the previous section.

START UP & CALIBRATION

B. POSITION FEEDBACK ALIGNMENT (Potentiometer)

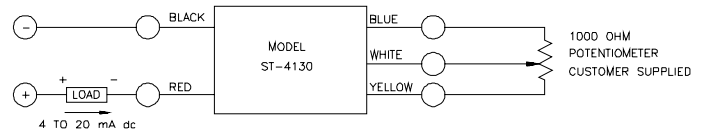
Position feedback is provided through the use of a potentiometer attached to the limit switch assembly. As the switches are driven by the actuator gearing, the potentiometer is simultaneously driven to provide position feedback.

1. Establish if full extend or full retract is to be used for zero indication. On slide gate installations, zero indication is normally used when the actuator is fully extended and the gate closed.
2. Make sure end of travel limit switches are correctly set for proper stroke length.
3. Use an ohmmeter to monitor the position of the feedback potentiometer wiper to determine which end of the pot gives a low ohm resistance indication.
4. If the reading is greater than 50 ohms, see Position Limit Switch Adjustment Procedure for actuators with a potentiometer.
5. Run the actuator through its stroke range to ensure the potentiometer is tracking through its electrical range. (Generally 60 to 90% of 1,000 ohms).

NOTE: On tandem potentiometer assembly, set the bottom potentiometer to approximately 50 ohms.

C. 4 to 20mA TRANSMITTER ADJUSTMENT

The ST-4130 (1000 ohm-input, 4 to 20mA output) two wire transmitter modulates the current on a direct current supply proportional to the input resistance. It is powered by a 12.0 to 36.0 Vdc unregulated power supply line which is modulated from 4 to 20mA proportional to the resistance of the input.



800 ohm maximum load when power supply is 24 Vdc

For the unit to function properly the 4mA end of the feedback potentiometer must be preset to 50 ohms.

1. Position the actuator to the desired 4mA setting. Resistance of the potentiometer must be measured without the ST-4130 connected.
2. With potentiometer resistance at 50 ohms, adjust ELEVATION for 4.0mA output.
3. Position the actuator to the desired 20mA setting.
4. Adjust RANGE for 20mA output.
5. Repeat steps 1 through 4 until no further adjustment is necessary.
6. To reverse the 4 and 20mA output, interchange the BLUE and YELLOW wires at the terminal block and return to step 1.

D. ACTUATOR WITH SERVO AMPLIFIERS

Switch and feedback device alignment is accomplished in the same manner as actuator without amplifiers, except motor power is supplied from the amplifier. Varying the command signal input to the amplifier will allow you to reverse the rotation of the actuator output shaft to run to the minimum/maximum switch settings. If the actuator does not run to the limit switch but stops short and both red lights are off on the amplifier board, the amplifier has nulled and adjustments of span, elevation, loss of signal, or feedback potentiometer may be required. Refer to IM-0607 for information on the AD-8130 series amplifier.

TROUBLESHOOTING GUIDE

TROUBLE	POSSIBLE CAUSE	REMEDY
Motor won't operate	a. No power to actuator	a. Check source, fuses, wiring
	b. Motor overheated and internal thermal switch tripped (single phase AC motors only)	b. Let motor cool and determine why overheating occurred (such as, excessive duty cycle or ambient temperature)
	c. Motor defective	c. Replace motor and determine cause of failure
	d. Both end of travel position limit switches open or one open and one defective	d. Adjust switch settings or replace defective switch
	e. Actuator ram stalled (mechanically jammed)	e. Check drive load for mechanical jam and correct cause
	f. Defective motor run capacitor (single phase ac motors only)	f. Replace capacitor
	g. Load exceeds actuator thrust rating	g. Reduce load or replace actuator with one with appropriate thrust rating
	h. Power applied to extend & retract at same time	h. Correct power input problem
	i. Amplifier defective	i. Replace amplifier
	j. Amplifier is in Loss of Signal	j. Check command signal to verify signal greater than 3.8 mA is present
	k. Amplifier deadband is too wide	k. Reduce deadband setting
Ram positions in wrong direction for extend and retract input power	a. Wiring to actuator incorrect	a. Correct field wiring
	b. Wiring from motor to terminals or switches is reversed	b. Correct internal actuator wiring
Motor hums, but does not run	a. Power applied to extend & retract at the same time	a. Correct power input problem
	b. Damaged power gearing	b. Repair gearing
	c. Defective motor run capacitor (single phase ac motors only)	c. Replace capacitor
	d. Damaged servo amplifier	d. Replace servo amplifier
Motor runs, but ram does not move	a. Defective power gearing	a. Repair gearing
	b. Screw drive nut stripped or pulled out of tube	b. Repair or replace screw drive nut
Motor does not shut off at limit switch	a. Switch wired wrong or is defective	a. Correct wiring or replace switch
	b. Switches are not aligned	b. Align switches

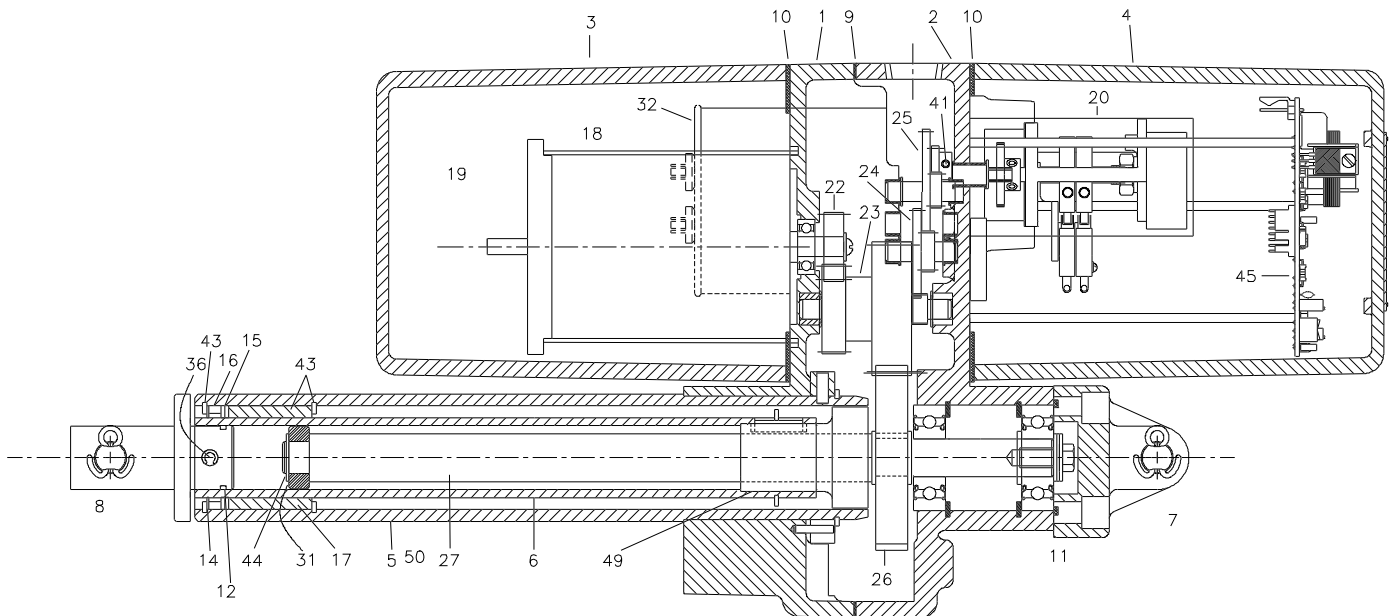
TROUBLESHOOTING GUIDE

TROUBLE	POSSIBLE CAUSE	REMEDY
Motor runs, but only one way	a. Power not applied for other direction	a. Correct power problem
	b. Power always applied to one direction and electrically stalls when applied for opposite direction	b. Correct power problem
	c. Open limit switch for other direction	c. Adjust or replace limit switch as required
	d. Motor has an open winding	d. Replace motor
	e. Motor and feedback potentiometer are out of phase	e. Reverse potentiometer end leads
	f. Amplifier is defective	f. Replace amplifier
Poor response to command signal changes	a. Amplifier deadband is too wide	a. Reduce deadband setting
	b. Amplifier is defective	b. Replace amplifier
	c. Excessive noise on command signal	c. Reduce noise. Also ensure that command signal wiring is shielded with shield grounded at source common only
Actuator oscillates at setpoint	a. Amplifier deadband is too narrow	a. Increase deadband setting
	b. Amplifier is defective	b. Replace amplifier
	c. Excessive noise on command signal	c. Reduce noise. Also ensure that command signal wiring is shielded with shield grounded at source common only
Pot feedback signal not always present during actuator ram movement	a. Pot not aligned with end of travel extremes and is being driven through its dead region	a. Align pot to range of actuator
	b. Pot signal is erratic or nonexistent	b. Replace pot
Pot signal does not change as actuator operates	a. Defective pot	a. Replace pot
	b. Feedback gear not turning pot shaft	b. Check gearing engagement and set screw in gear hub
Pot signal is reversed for output ram direction	a. Pot is wired wrong	a. Reverse wiring from ends of pot at actuator terminal block
Water droplets inside motor area of actuator	a. Condensation caused by temperature variations and humidity	a. Add heater and thermostat circuit and ensure that existing circuit is continuously energized. Check conduit entry and seal to prevent water from entering via the conduit
	b. Water entering actuator	b. Ensure rear cover gasket is in place and replace if defective. Also ensure all cover bolts are in place and tightened. Check conduit entry and seal to prevent water from entering via the conduit

Note: For actuators controlled by internal or remote servo-amplifiers, refer to that servo-amplifier's instruction manual for additional troubleshooting information.

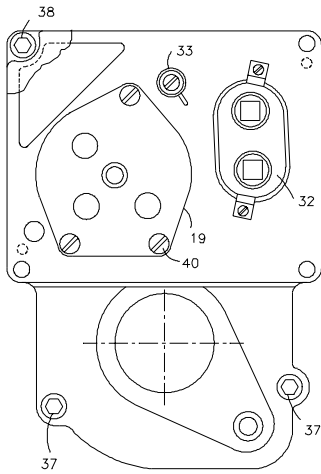
COMPONENT IDENTIFICATION

- | | |
|--------------------------------|-------------------------------------------|
| 1. Motor Housing | 18. Motor |
| 2. Feedback Housing | 19. Motor Top (1 phase ac only) |
| 3. Motor Cover | 20. Feedback Assembly |
| 4. Feedback Cover | 22. Motor Pinion |
| 5. Outer Tube | 23. Power Idler Gear Assembly |
| 6. Inner Tube Assembly | 24. Feedback Idler Gear Assembly |
| 7. Clevis, Stationary | 25. Limit Switch Gear |
| 8. Clevis, Tube | 26. Drive Screw Gear |
| 9. Housing Gasket | 27. Drive Screw |
| 10. Cover Gasket | 31. Drive Screw Guide |
| 11. O' Ring, Stationary Clevis | 36. Tube Clevis Roll Pin |
| 12. O' Ring, Tube Clevis | 41. Limit Switch Gear Set Screws |
| 14. Tube Scraper | 42. Limit Switch Assembly Mounting Screws |
| 15. Tube Seals | 43. Tube Bearing and Seal Retaining Ring |
| 16. Tube Spacer | 44. Drive Screw Guide Retaining Ring |
| 17. Tube Bearing | 49. Drive Nut |

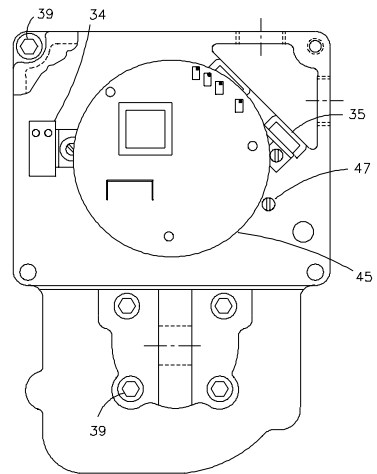


COMPONENT IDENTIFICATION

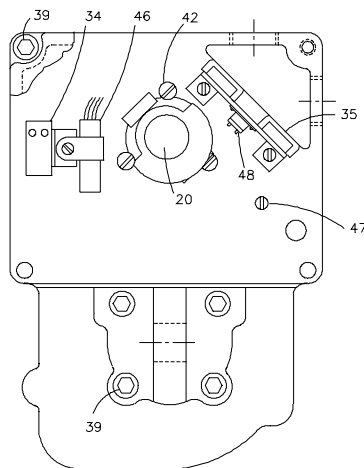
AC Motor Side (1 phase)



Feedback Side with Amp



Feedback Side



- | | |
|----------------------------------------------|--------------------------|
| 18. Motor | 37. Housing Bolts |
| 19. Motor Top (1 phase ac only) | 38. Motor Cover Bolts |
| 20. Feedback Assembly | 39. Feedback Cover Bolts |
| 32. AC Motor Capacitor (1 phase ac only) | 40. Motor Mounting Bolts |
| 33. AC Motor Resistor (1 phase ac only) | 45. AD-8130 Amplifier |
| 34. ST-4130 Loop Powered 4-20 mA Transmitter | 46. Heater |
| 35. Terminal Strip | 47. Ground Screw |
| | 48. Thermo Switch |

MAINTENANCE

Under normal service conditions, the motor, gearing, bearings, and parts do not require periodic maintenance. If for any reason the unit is disassembled in the field, all Oilite bushings should be saturated with S.A.E. 20 or 30 non-detergent oil and all gearing heavily coated with Amoco-Amolith Rykon all weather premium grease #2 or equal.

Care should be taken to ensure that no foreign material is in the grease, which could cause premature failure. The screw shaft must be lubricated with Allex EP1L grease. DO NOT SUBSTITUTE.

Refer to Pages 13 and 14 for component locations.

To Separate Housings:

- A. Disconnect motor wires which run through housing.
- B. Extend front clevis to obtain access to roll pin 36.
- C. Remove roll pin 36 and front clevis 8.
- D. Remove housing screws 37, 38 and 39.
- E. Separate housing assemblies and remove gears 23 and 24.

To Remove Motor 18:

- A. Separate housings.
- B. If gear 22 is held to motor shaft with a retaining ring, remove the ring and gear 22.
- C. Remove screws 40.
- D. Remove motor top 19. (ac motor only).
- E. Remove motor stator and rotor 18.

To Remove Multi-turn Feedback Assembly 20:

- A. Separate housings.
- B. Loosen set screws 41 and remove gear 25.
- C. Remove screws 42.
- D. Remove feedback assembly 20.

To Remove Single-turn Feedback Assembly 20:

- A. Separate housings.
- B. Loosen set screws 41 and remove gear 25.
- C. Remove screws 42.
- D. Remove feedback assembly 20.

To Change Tube Bearing 17 or Seals 15:

- A. Separate housings.
- B. Remove outer retaining ring 43.
- C. Remove scraper 14, spacer 16, seals 15 and tube bearing 17.

To Remove Inner Tube Assembly 6:

- A. Separate housings.
- B. Remove retaining ring 44 and guide 31.
- C. Hold screw shaft gear 26 and turn tube 6 to unscrew from shaft.

Power Gearing Selection Chart

(All Stroke Lengths)

Stroke Speed	Motor Pinion Gear	Power Idler Gear Assembly
0.1" + 0.2"/sec.	16A-039971-004	65A-039544-001
0.4" + 0.4"/sec.	16A-039971-003	65A-039544-002
0.2" + 0.8"/sec.	16A-039971-002	65A-039544-003
0.6" + 2.0"/sec.	16A-039971-001	65A-039544-004

Single Turn Feedback Gearing & Drive Nut Selection Charts

LA-2315, LA-2320, LA-2390 (0.2"/sec. & 0.4"/sec.)

Stroke	1st Stage Gear	2nd Stage Gear	Limit Switch Gear	Drive Nut (3/4 - 10)
3"	65B-025344-007	N/A	16B-003803-149	61A-039553-001
4"	65B-025344-009	N/A	16B-003803-151	61A-039553-001
6"	65A-017619-008	N/A	16B-003803-150	61A-039553-001
9"	65A-017619-001	65A-021042-001	16B-021043-001	61A-039553-001
12"	65A-017619-001	65A-017620-002	16B-003803-112	61A-039553-001
18"	65A-017619-001	65A-021042-002	16B-003803-150	61A-039553-001
24"	65A-017619-001	65A-021042-005	16B-003803-133	61A-039553-001
30"	65A-017619-001	65A-021042-006	16B-003803-132	61A-039553-001
36"	65A-017619-001	65A-021042-007	16B-003803-132	61A-039553-001

LA-2315, LA-2320, LA-2390 (0.8"/sec. & 2.0"/sec.)

Stroke	1st Stage Gear	2nd Stage Gear	Limit Switch Gear	Drive Nut (3/4 - 6)
6"	65B-025344-003	N/A	16B-003803-131	61A-039553-001
7"	65B-025344-003	N/A	16B-003803-001	61A-039553-001
12"	65B-025344-002	N/A	16B-003803-132	61A-039553-001
15"	65B-025344-002	N/A	16B-003803-132	61A-039553-001
18"	65B-025344-008	N/A	16B-003803-150	61A-039553-001
22"	65B-025344-008	N/A	16B-003803-150	61A-039553-001
24"	65A-017619-001	65A-021042-001	16B-021043-001	61A-039553-001
30"	65A-017619-001	65A-021042-001	16B-021043-001	61A-039553-001
36"	65A-017619-001	65A-017620-003	16B-003803-042	61A-039553-001
11"	65B-025344-007	N/A	16B-003803-149	61A-039553-001

PARTS LIST

Recommended Spare Parts Indicated in Bold

ID	Description	Part Number	Quantity
1	Motor Housing - ac Units	60D-039552-001	1
2	Feedback Housing	60D-023767-001	1
3	Motor Cover	60D-039551-001	1
4	Feedback Cover w/o Amp	60C-016328-001	1
	Feedback Cover with Amp	60C-016326-001	1
	(or with 21P option)		
5	Outer Tube, 6" stroke	61B-039535-001	1
	Outer Tube, 12" stroke	61B-039535-002	1
	Outer Tube, 18" stroke	61B-039535-003	1
6	Inner Tube, 6" stroke	61B-039536-001	1
	Inner Tube, 12" stroke	61B-039536-002	1
	Inner Tube, 18" stroke	61B-039536-003	1
	Tube Bearing	61A-039686-001	1
	Retaining Ring	58B-039763-029	1
	Retaining Ring	58B-014185-162	2
	Key	58B-024244-447	1
	Shim Spacer	13A-014549-006	A/R
7	Rear Clevis, Forked	60B-039539-001	1
8	Front Clevis, Forked	61A-039714-001	1
9	Gasket, Main Housing	13C-016366-001	1
10	Gasket, Cover	13B-016367-001	2
11	O Ring, Rear Clevis	74B-010957-133	1
12	O Ring, Front Clevis	74B-010957-020	1
14	Scraper	13A-012877-001	1
15	Seal	19A-012878-000	2
16	Adaptor Seal	61A-012876-001	1
17	Tube Bearing	61A-039686-001	1
18	Motor, LA-2315, 0.2" or 0.8" / sec.	23B-037613-002	1
	Motor, LA-2315, 0.4" or 2.0" / sec.	23B-037614-002	1
	Motor, LA-2320, 0.2" or 0.8" / sec.	61B-015764-008	1
	Motor, LA-2320, 0.4" or 2.0" / sec.	61B-015764-010	1
	Motor, LA-2390, 0.2" or 0.8" / sec.	61B-015764-009	1
	Motor, LA-2390, 0.4" or 2.0" / sec.	61B-015764-011	1
19	Motor Top (1 phase ac units only)	60C-012753-003	1
	Belleville Washers (1 phase ac units only)	56A-005478-001	4
20	Single Turn Feedback:		
	Position Limit Switch, SPDT	46B-004053-405	2
	Position Limit Switch, DPDT	46B-004053-414	2
	1K Potentiometer	34B-0033104-001	1
	1K/1K Potentiometer	34B-003956-160	1

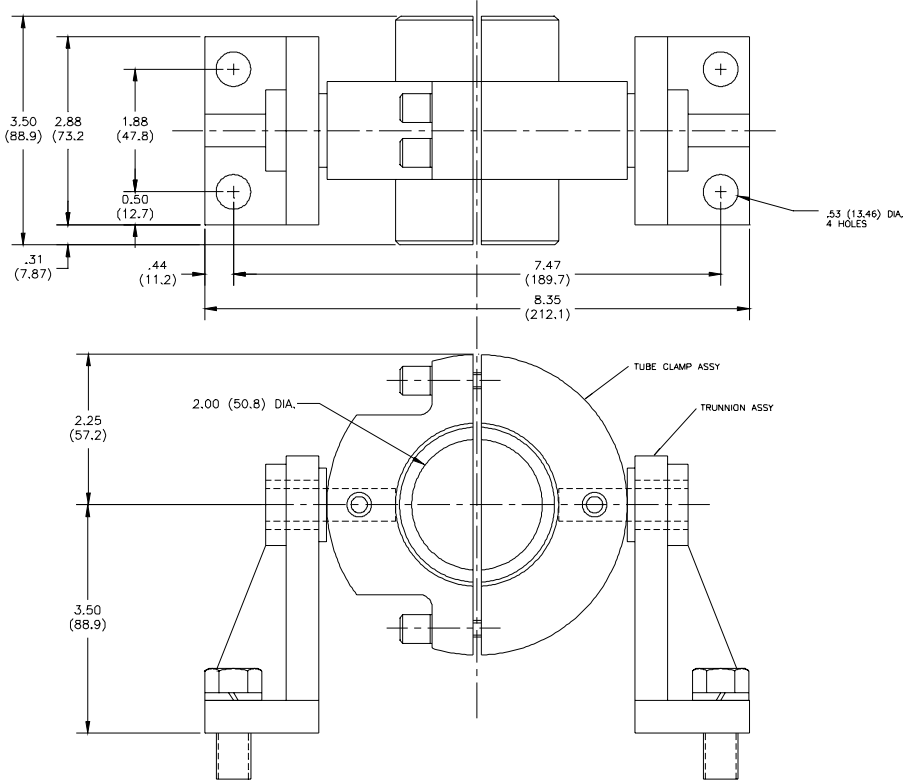
PARTS LIST

Recommended Spare Parts Indicated in Bold

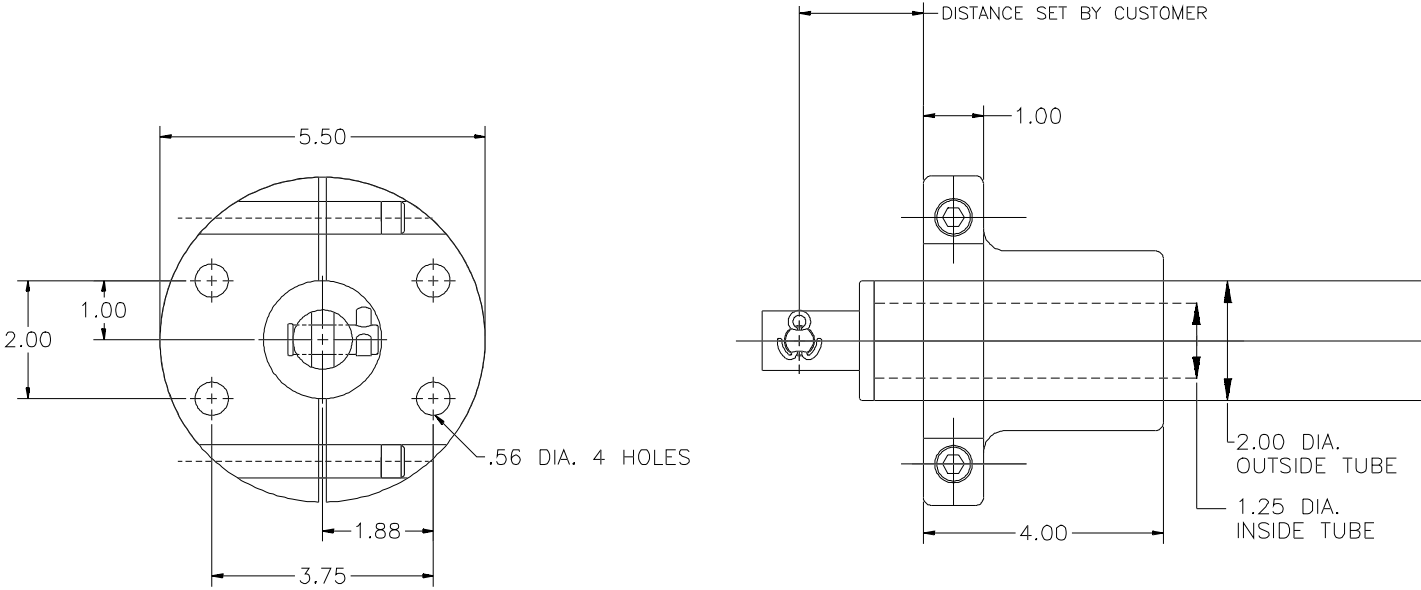
ID	Description	Part Number	Quantity
22	Motor Pinion Gear	See Selection Chart	1
23	Power Idler Gear Assembly	See Selection Chart	1
24	Feedback Gearing	See Selection Chart	1
25	Limit Switch Gear	See Selection Chart	1
26	Screw Gear, 0.2" or 0.4" / sec.	16B-039550-002	1
	Screw Gear, 0.8" or 2.0" / sec.	16B-039550-001	1
27	Drive Screw:		
	6 inch, 3/4 - 8	62C-039558-001	1
	12 inch, 3/4 - 8	62C-039558-002	1
	18 inch, 3/4 - 8	62C-039558-003	1
	24 inch, 3/4 - 8	62C-039558-004	1
	30 inch, 3/4 - 8	62C-039558-005	1
	36 inch, 3/4 - 8	62C-039558-006	1
31	Drive Screw Guide	14A-012868-001	1
32	Capacitor:		
	10 mfd, LA-2390	24B-029812-008	1
	40 mfd, LA-2320	24B-029812-020	1
33	Resistor, LA-2420, LA-2490	33B-003852-305	1
34	ST-4130 Transmitter	70A-019948-001	1
35	Terminal Block	43B-035496-002	2
36	Roll Pin	57A-015205-063	1
37	Cap Screw	54A-015070-175	2
38	Cap Screw	54A-015070-200	4
39	Cap Screw	54A-015070-100	4
40	Screw, LA-2320, LA-2390	54A-015004-500	3
41	Set Screw	54A-015037-019	2
42	Screw, Truss Head	54A-015032-025	3
43	Retaining Ring	58B-014185-162	2
44	Retaining Ring	58B-014183-050	1
45	AD-8130 Amplifier	68C-035658-001	1
46	Heater, 120 Vac	74A-016946-001	1
	Heater, 240 Vac	74A-031965-001	1
47	Ground Screw	58B-024244-152	1
48	Thermoswitch	74A-023565-001	1
49	Drive Nut	See Selection Chart	1
50	Screw Shaft Grease	73A-032878-001	1

INSTALLATION DIMENSIONS

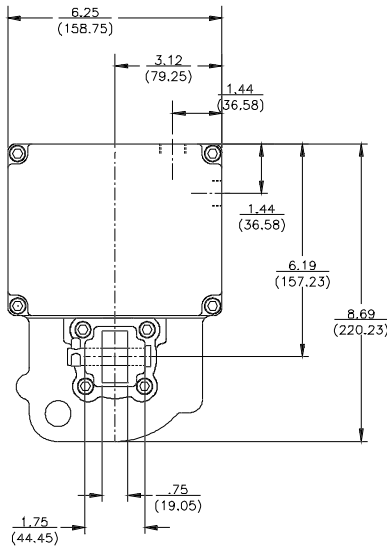
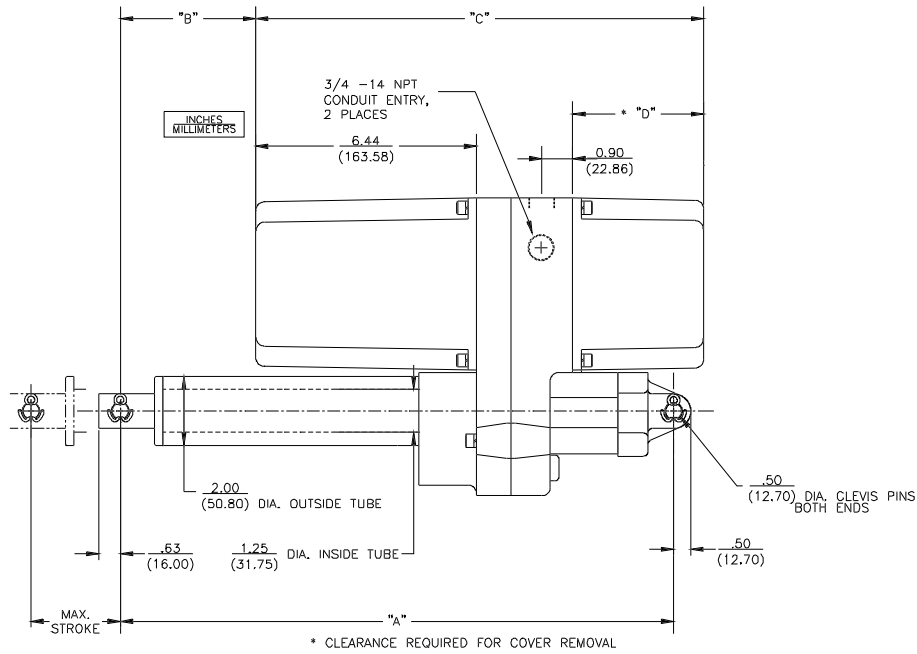
(Trunnion Mount)



(Flange Mount)



LA-2300 MAJOR DIMENSIONS



Stroke in. (mm)	A	B	C	D	
				Without Amp	With amp
6 (152)	15.43 (392)	2.83 (72)	6 max. (152)	3.81 (97)	6.44 (164)
12 (305)	21.43 (544)	8.83 (224)	12 max. (305)	3.81 (97)	6.44 (164)
18 (457)	27.43 (697)	14.83 (377)	18 max. (457)	3.81 (97)	6.44 (164)
24 (609)	33.43 (849)	20.83 (529)	24 max. (609)	3.81 (97)	6.44 (164)
30 (762)	39.43 (1002)	26.83 (681)	30 max. (762)	3.81 (97)	6.44 (164)
36 (914)	45.43 (1154)	32.83 (834)	36 max. (914)	3.81 (97)	6.44 (164)

These dimensions are subject to change without notice and should not be used for preparation of drawings or fabrication of installation mounting. Current installation dimension drawings are available on request.

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JORDAN CONTROLS, INC.
5607 West Douglas Avenue
Milwaukee, Wisconsin 53218
Phone: (414) 461-9200
FAX: (414) 461-1024
E-Mail: jordan@jordancontrols.com
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